

# A Simple Application of Variational Bayes

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Consider the following model:

$$\begin{aligned}x_i &\sim N(\mu, \sigma^2), & i = 1, \dots, n \\ \mu &\sim N(\mu_0, \sigma_0^2) \\ \sigma^2 &\sim \text{Inv-Gamma}(\alpha, \beta)\end{aligned}$$

$$P(\mu, \sigma^2 | x) = \frac{P(\mu, \sigma^2, x)}{P(x)}$$

where

$$P(\mu, \sigma^2, x) = \sigma^{-1} \exp\left[-\frac{\sum(x_i - \mu)^2}{2\sigma^2}\right] \exp\left[-\frac{(\mu - \mu_0)^2}{2\sigma_0^2}\right] (\sigma^2)^{-\alpha-1} \exp\left[-\frac{\beta}{\sigma^2}\right]$$

As an illustrative example, we set  $\mu = -1$  and  $\sigma^2 = 1$ . We generate 5 random samples from  $N(-1, 2)$ . Given these samples as observed data, the posterior distribution,  $P(\mu, \sigma^2 | x)$ , based on Gibbs sampling is shown in Figure 1. Our goal is to approximate this distribution with  $Q(\mu, \sigma^2 | \theta)$ . We assume

$$Q(\mu, \sigma^2 | \theta) = Q(\mu | \theta) Q(\sigma^2 | \theta)$$

More specifically, we assume

$$\begin{aligned}Q(\mu | m, v) &= N(m, v^2) \\ Q(\sigma^2 | a, b) &= \text{Inv-Gamma}(a, b) \\ Q(\mu | m, v) Q(\sigma^2 | a, b) &\propto v^{-1} \exp\left[-\frac{(\mu - m)^2}{2v^2}\right] \cdot \frac{b^a}{\Gamma(a)} (\sigma^2)^{-a-1} \exp\left(-\frac{b}{\sigma^2}\right)\end{aligned}$$

We minimize  $-\mathcal{L}(Q)$  with respect to  $\theta = (m, v, a, b)$ ,

$$\mathcal{L}(Q) = E_Q[\log P(\mu, \sigma^2, x)] - E_Q[\log Q(\mu, \sigma^2 | \theta)]$$

subject to  $v, a, b > 0$ . We have

$$\begin{aligned}\log P(\mu, \sigma^2, x) &= -n \log \sigma - \frac{\sum(x_i - \mu)^2}{2\sigma^2} - \frac{(\mu - \mu_0)^2}{2\sigma_0^2} - (\alpha + 1) \log \sigma^2 - \frac{\beta}{\sigma^2} \\ \log Q(\mu, \sigma^2 | \theta) &= -\log v - \frac{(\mu - m)^2}{2v^2} + a \log b - \log \Gamma(a) - (a + 1) \log \sigma^2 - \frac{b}{\sigma^2}\end{aligned}$$

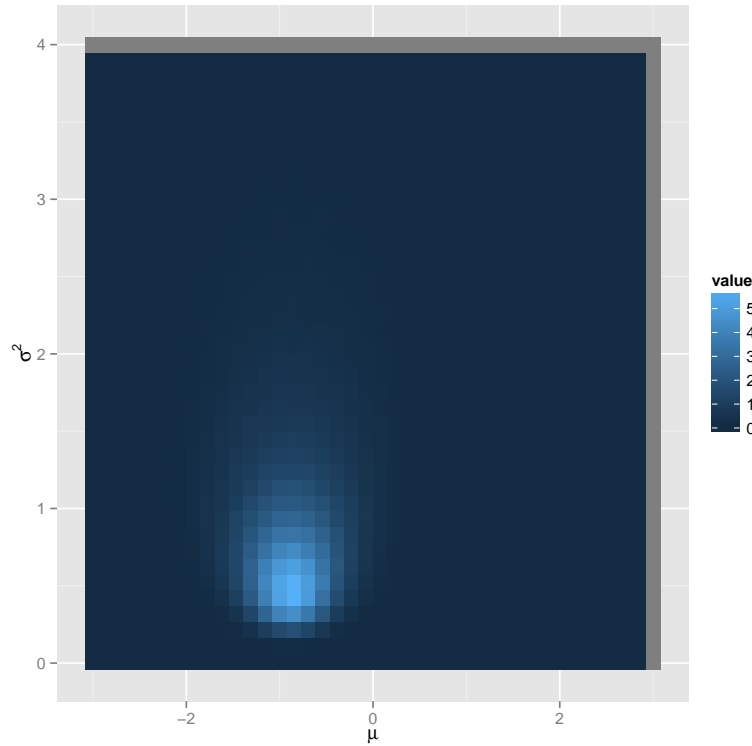


Fig 1: Posterior distribution of  $(\mu, \sigma^2)$  using the Gibbs sampler.

Note that for Inv-Gamma distribution, we have

$$E_Q\left(\frac{1}{\sigma^2}\right) = a/b$$

$$E_Q(\log \sigma^2) = \log b - \psi(a)$$

where  $\psi$  is the digamma function, whose derivative is  $\psi_1$ , the trigamma function.

We start by minimizing  $-\mathcal{L}(Q)$  with respect to  $m$  and  $v$  keeping  $a$  and  $b$  fixed at their current

values. We have

$$\begin{aligned}
E_Q[\log P(\mu, \sigma^2, x)] &= E\left[-\frac{\Sigma(x_i - \mu)^2}{2\sigma^2} - \frac{(\mu - \mu_0)^2}{2\sigma_0^2}\right] \\
&= -\frac{1}{2}E\left(\frac{1}{\sigma^2}\right)(nv^2 + \Sigma(x_i - m)^2) - \frac{1}{2\sigma_0^2}(v^2 + (\mu_0 - m)^2) \\
&= -\frac{a}{2b}(nv^2 + \Sigma(x_i - m)^2) - \frac{1}{2\sigma_0^2}(v^2 + (\mu_0 - m)^2) \\
E_Q[\log Q(\mu, \sigma^2|\theta)] &= -\log v - \frac{1}{v^2}v^2 \\
&= -\log v - \frac{1}{2}
\end{aligned}$$

Therefore,

$$\mathcal{L}(Q) = -\frac{a}{2b}(nv^2 + \Sigma(x_i - m)^2) - \frac{1}{2\sigma_0^2}(v^2 + (\mu_0 - m)^2) + \log v + \frac{1}{2}$$

Next we find the partial derivatives of  $\mathcal{L}(Q)$  with respect to  $m$  and  $v$ ,

$$\begin{aligned}
\partial\mathcal{L}(Q)/\partial m &= \frac{-a}{2b}(2nm - 2\Sigma x_i) - \frac{1}{2\sigma_0^2}(2m - 2\mu_0) \\
&= \frac{-a}{b}(nm - \Sigma x_i) - \frac{1}{\sigma_0^2}(m - \mu_0) \\
\partial\mathcal{L}(Q)/\partial v &= -\frac{a}{b}nv - \frac{v}{\sigma_0^2} + \frac{1}{v} \\
&= \left(-\frac{an}{b} - \frac{1}{\sigma_0^2}\right)v + \frac{1}{v}
\end{aligned}$$

Next, we minimize  $-\mathcal{L}(Q)$  with respect to  $a$  and  $b$  keeping  $m$  and  $v$  fixed at their current values. We have

$$\begin{aligned}
E_Q[\log P(\mu, \sigma^2, x)] &= -\frac{n}{2}E(\log \sigma^2) - \frac{nv^2 + \Sigma(x_i - m)^2}{2}E\left(\frac{1}{\sigma^2}\right) - (\alpha + 1)E(\log \sigma^2) - \beta E\left(\frac{1}{\sigma^2}\right) \\
&= -\frac{n}{2}[\log b - \psi(a)] - \frac{nv^2 + \Sigma(x_i - m)^2}{2} \frac{a}{b} - (\alpha + 1)[\log b - \psi(a)] - \beta \frac{a}{b} \\
&= -(\alpha + n/2 + 1)[\log b - \psi(a)] - \frac{nv^2 + \Sigma(x_i - m)^2 + 2\beta a}{2} \frac{a}{b} \\
E_Q[\log Q(\mu, \sigma^2|\theta)] &= -\frac{1}{2} + a \log b - \log \Gamma(a) - (a + 1)[\log b - \psi(a)] - a
\end{aligned}$$

Therefore,

$$\mathcal{L}(Q) = (a - \alpha - n/2)[\log b - \psi(a)] - \frac{nv^2 + \Sigma(x_i - m)^2 + 2\beta a}{2} \frac{a}{b} + \frac{1}{2} - a \log b + \log \Gamma(a) + a$$

We now find the partial derivatives with respect to  $a$  and  $b$ ,

$$\begin{aligned}\partial\mathcal{L}(Q)/\partial a &= \log b - \psi(a) - (a - \alpha - n/2)\psi_1(a) - \frac{nv^2 + \Sigma(x_i - m)^2 + 2\beta}{2b} - \log b + \psi(a) \\ &= -(a - \alpha - n/2)\psi_1(a) - \frac{nv^2 + \Sigma(x_i - m)^2 + 2\beta}{2b} \\ \partial\mathcal{L}(Q)/\partial b &= \frac{a - \alpha - n/2}{b} + \frac{nv^2 + \Sigma(x_i - m)^2 + 2\beta}{2} \frac{a}{b^2} - \frac{a}{b} \\ &= \frac{-\alpha - n/2}{b} + \frac{a[nv^2 + \Sigma(x_i - m)^2 + 2\beta]}{2b^2}\end{aligned}$$

We can simply use the coordinate descent algorithm (Luo and Tseng, 1992) to find  $Q$ . For simplicity, we assume  $a = 1$  and minimize  $-\mathcal{L}(Q)$  in terms of  $m, v$ , and  $b$  as follows:

$$\begin{aligned}\partial\mathcal{L}(Q)/\partial m &= \frac{-a}{b}(nm - \Sigma x_i) - \frac{1}{\sigma_0^2}(m - \mu_0) = 0 \\ m &= \frac{n\bar{x} + \frac{b}{a}\frac{\mu_0}{\sigma_0^2}}{(n + \frac{b}{a}\frac{1}{\sigma_0^2})} \\ \partial\mathcal{L}(Q)/\partial v &= \left(-\frac{an}{b} - \frac{1}{\sigma_0^2}\right)v + \frac{1}{v} = 0 \\ v &= \sqrt{\frac{\frac{b}{a}}{n + \frac{b}{a}\frac{1}{\sigma_0^2}}} \\ \partial\mathcal{L}(Q)/\partial b &= \frac{-\alpha - n/2}{b} + \frac{a[nv^2 + \Sigma(x_i - m)^2 + 2\beta]}{2b^2} = 0 \\ b &= \frac{a[nv^2 + \Sigma(x_i - m)^2 + 2\beta]}{2\alpha + n}\end{aligned}$$

Therefore, we use Algorithm 1 for updating the parameters.

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**Algorithm 1** Coordinate descent algorithm

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Initialize  $m, v$  and  $b$

**for**  $\ell = 1$  to  $L$  **do**

$$m^{(\ell+1)} = \frac{n\bar{x} + \frac{b^{(\ell)}}{a}\frac{\mu_0}{\sigma_0^2}}{(n + \frac{b^{(\ell)}}{a}\frac{1}{\sigma_0^2})}$$

$$v^{(\ell+1)} = \sqrt{\frac{\frac{b^{(\ell)}}{a}}{n + \frac{b^{(\ell)}}{a}\frac{1}{\sigma_0^2}}}$$

$$b^{(\ell+1)} = \frac{a[n[v^{(\ell+1)}]^2 + \Sigma(x_i - m^{(\ell+1)})^2 + 2\beta]}{2\alpha + 1}$$

**end for**

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The approximate posterior distribution is shown in Figure 2.

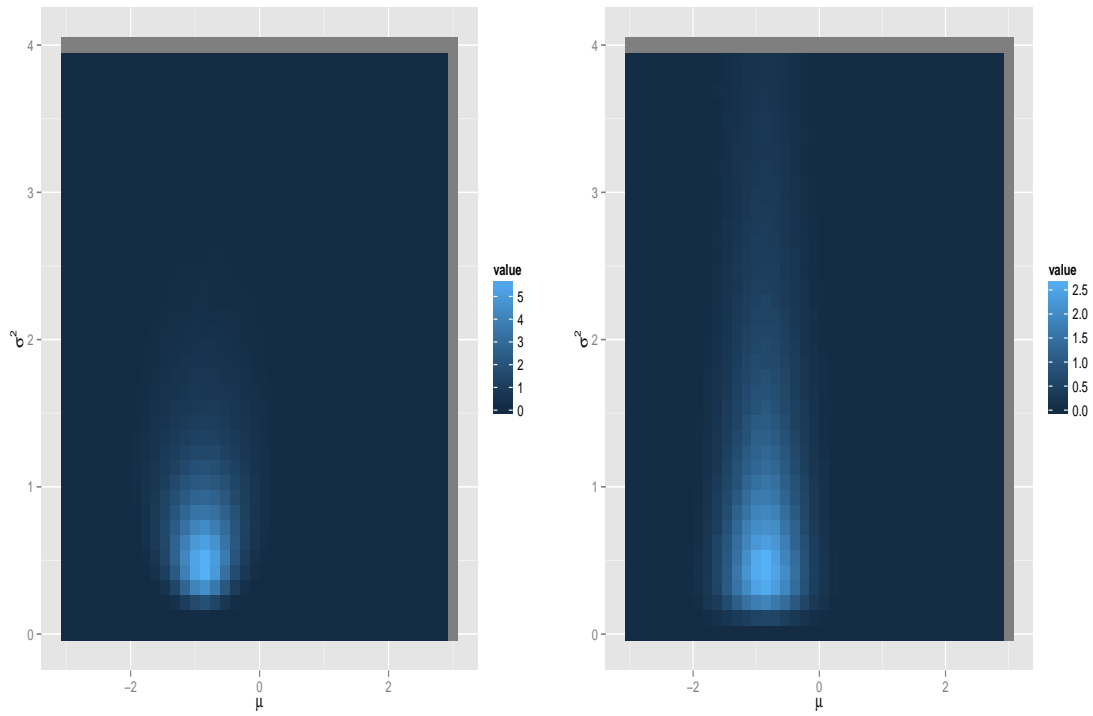


Fig 2: Approximate posterior distribution using variational Bayes. Left panel: True posterior distribution; Right panel: Variational Bayes approximation.